

# E

To-Type SMD Programmable AD Pyroelectric Infrared Sensors

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S23-S340R

V1.

## 1.

### 1.1

ISO14001

ISO14001

ISO 9001

ISO

- “ ISO 9001 ”

### 1.2

ROHS

ROHS

“  
ROHS

2011/65/EC ”

### 1.3

1.3.1

1.3.2

IC

PIR

MCU

S23-S340R

MCU

MCU

MCU

PIR

14

## 2.

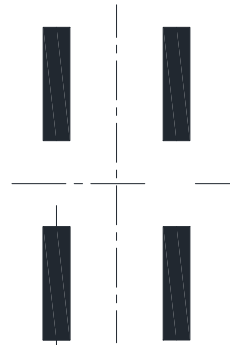
### 3.2

SMD

### 3.3

USB

### 3.4



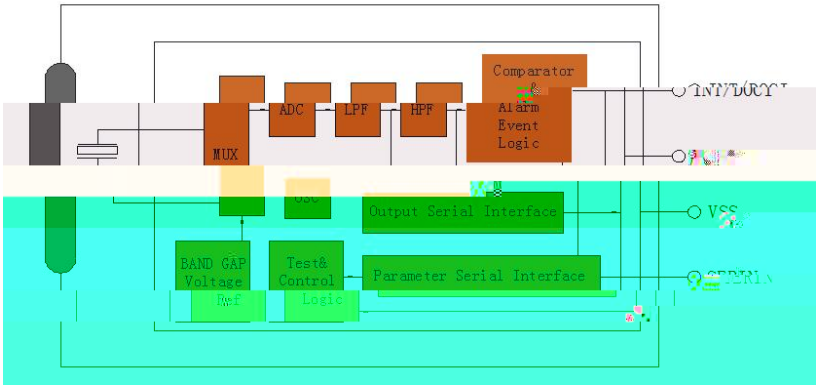
1

±

(unit): mm

3.5

|  |           |         |        |               |  |
|--|-----------|---------|--------|---------------|--|
|  |           |         |        |               |  |
|  | TST       | -20     | 70     |               |  |
|  | $\theta$  | X=120 ° | Y=90 ° | °             |  |
|  | TST       | -30     | 80     |               |  |
|  | $\lambda$ | 5       | 14     | $\mu\text{m}$ |  |



3.6 ( VDD = +3V TAMB = +25 50 ± 10%)

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### 3.7

S23-S340R                      PIR

                                         ADC

#### 3.7.1.

- 1    MUX                                              ADC                                              PIR
  
- 2                                              (BAND GAP Volatage Ref)
  
- 3                                              (OSC)                                              64kHz
  
- 4                                              (LPF HPF)                                              7Hz                                              0.4Hz
  
- 5                                              (Comparator&Alarm Event Logic)



0 =                      1 =

7) ADC

|     |       |       |
|-----|-------|-------|
| ADC | ADC   | :     |
| PIR | BFP   | = 0   |
| PIR | LPF   | = 1   |
|     | = 2   |       |
|     | = 3   |       |
|     | " 0 " | " 1 " |

8)

9

1=                      0=

3.7.3

(0

DR

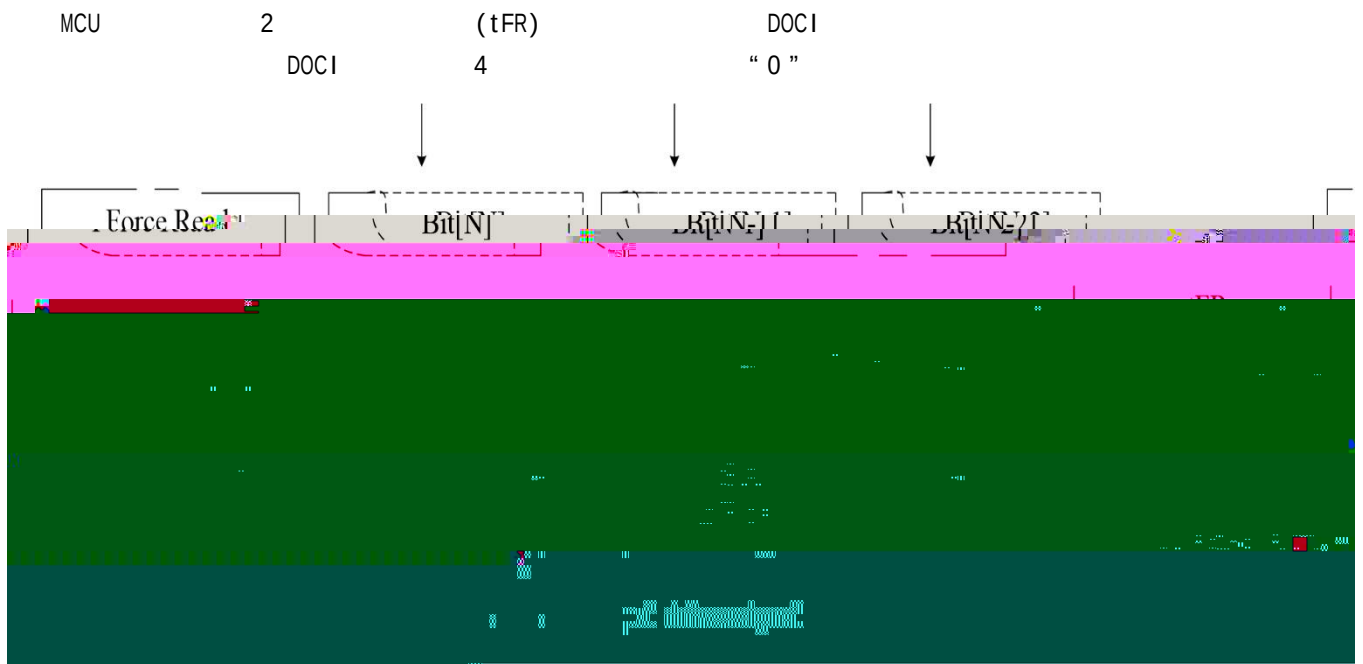
RIN

SERIN

0      1

### 3.7.4

### DOCI



ADC

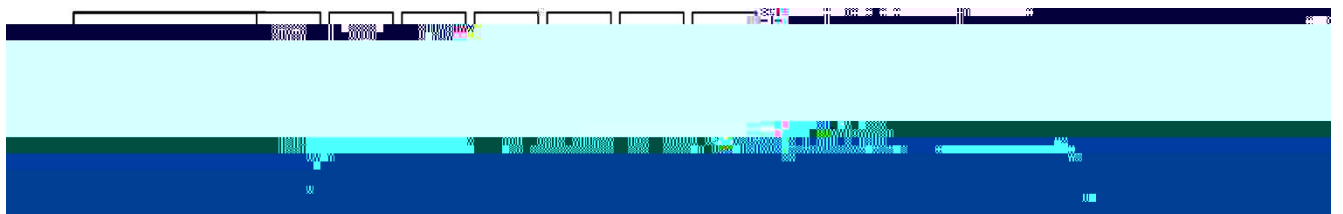
DOCI / INTR

ADC

512

PIR

DOCI





|       |           |                                                              |
|-------|-----------|--------------------------------------------------------------|
| [6:5] | [1:0] ADC | 0 = PIR (HPF)    1 = PIR (LPF)<br>2 =                    3 = |
| [4:1] |           |                                                              |
| [0]   |           | 1=                    0=                                     |

### 3.8

### 3.8.1 PIR

1)

$$V_{PIR} = (ADC\_out - ADC\_offset) * 6.5\mu v$$

2)

ADC [6:5] PIR HPF ( =0)  
VPIR = ADC\_out \* 6.5μv

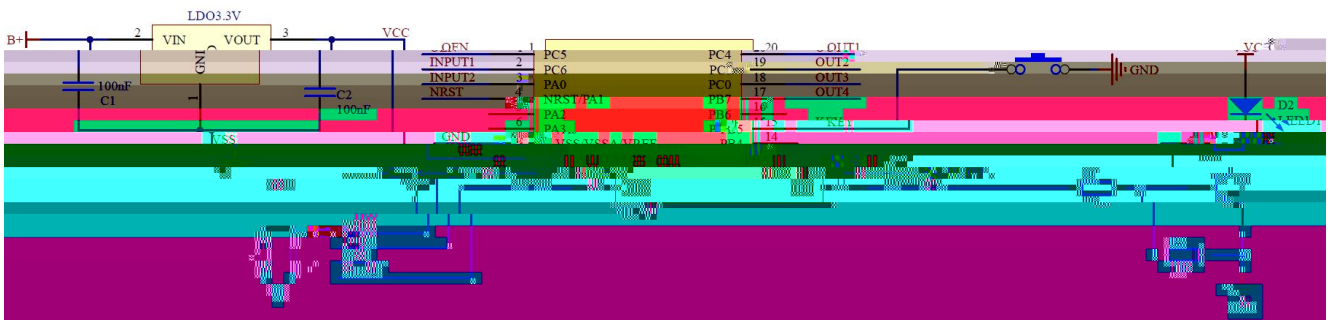
### 3.8.2

$$V_{DD} = (ADC\_out - ADC\_offset) * 650\mu V.$$

### 3.8.3

$$\begin{aligned} \text{ADC} \quad [6:5] & \quad ( \quad = 3) \\ & = \text{Tcal} + (\text{ADC\_out} - \text{ADC\_offset}(\text{Tcal})) / 80 * \text{count} / K \\ \text{ADC\_offset} & = \text{ADC} \quad @ \text{VIN} = 0 \quad = 2^{13} \\ \text{ADC\_offset}(\text{Tcal}) & = \quad \text{ADC} \quad = 8200 @ 300k \end{aligned}$$

4.





7.1.6

SO<sub>2</sub>

CL<sub>2</sub>, NO<sub>x</sub>

7.1.7

72h

40 ± 10%RH

7.1.8

3

## 7.2

7.2.1

7.2.1.1

7.2.1.2

7.2.1.3

7.2.1.4

1

SO<sub>2</sub> CL<sub>2</sub>, NO<sub>x</sub>

2

3

4

5

6

7

8

7.2.2

1

2

3

4

5 \*

6

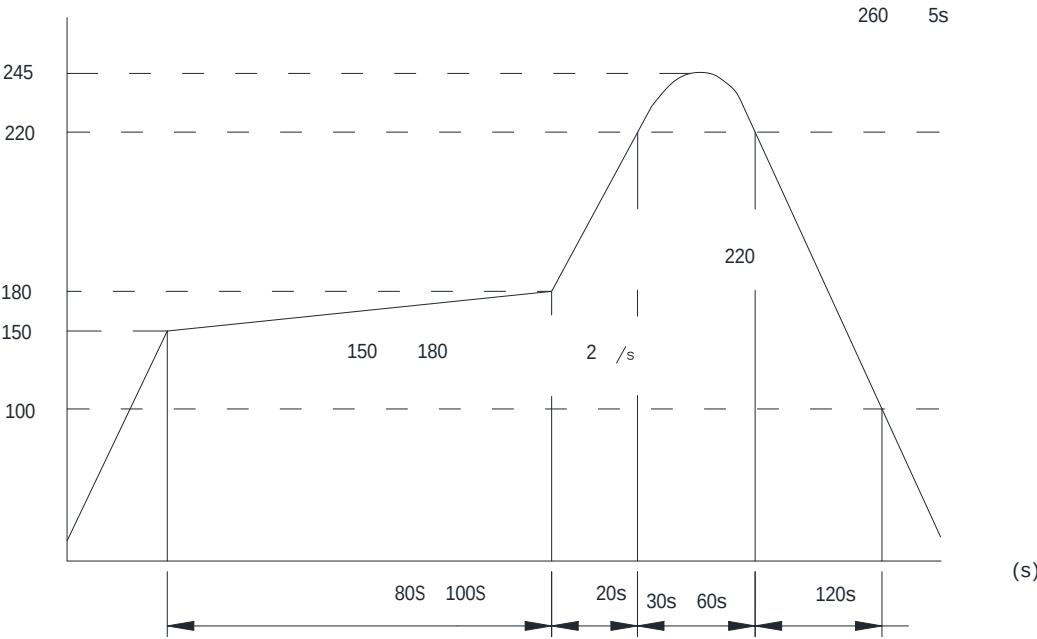
7

8

7.3

|       |     |     |   |
|-------|-----|-----|---|
| 7.3.1 | 7   |     |   |
| 7.3.2 | PIR | PIR | 3 |

|       |
|-------|
| 7.3.3 |
| 7.3.4 |



- 1
- 2 \*
- 3 \*
- 4 \*

“ ”